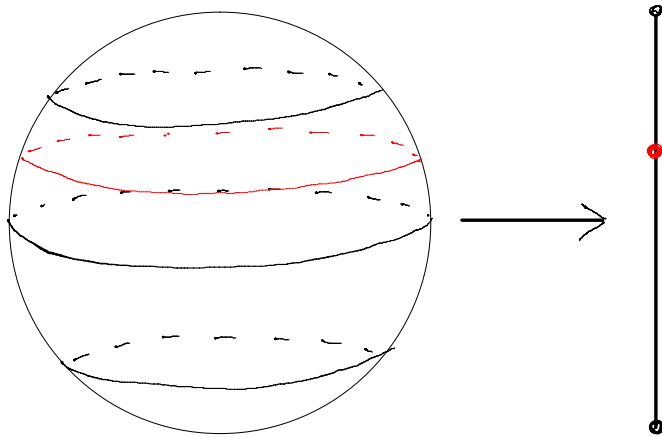


I. Toric symplectic manifolds & Delzant construction.
(GGTI Online Seminar on toric symplectic manifolds)



Johannes BRENDL — Université de Neuchâtel (23 August 2021)

- Outline :
- §0. Symplectic geometry & Ham. torus actions
 - §1. Toric manifolds
 - §2. Example: $\mathbb{C}P^2$
 - §3. Symplectic Reduction
 - §4. The Delzant construction.

(Exercises: green stars (*) & see last slide.)

- References :
- *) A. Cannas da Silva — Symplectic toric manifolds.
 - *) E. Meinrenken — Symplectic geometry (script)
 - *) J. Evans — Lagrangian torus fibrations
 - *) V. Guillemin — Moment maps and combinatorial invariants of Hamiltonian T^n -spaces.
 - *) M. Andin — Torus actions on sympl. manifolds.

§ 0. Overview: Symplectic manifolds & Hamiltonian torus actions.

Def: Let (M, ω) be a **symplectic manifold**, i.e. 1) $\omega \in \Omega_{ce}^2(M)$
2) ω non-degen.
 $TM \xrightarrow{\cong} T^*M, \quad X \mapsto \iota(X)\omega = \omega(X, \cdot)$

Let $H: M \rightarrow \mathbb{R}$ smooth function. Can associate a vector field $X_H \in \mathfrak{X}(M)$ to H by setting

$$\boxed{dH = \iota(X_H)\omega} \quad (\text{Hamilton's equation})$$

Def: The function H is called **Hamiltonian (function)**.
The vector field X_H is called **Hamiltonian vector field**.
Its flow $\phi_H^t: M \rightarrow M$ is called **Hamiltonian flow**.

Rk: In general, Hamiltonians may be time-dependent.

Hamiltonian flows

- 1) preserve the symplectic form, $(\phi_t^*)^* \omega = \omega$
- 2) preserve their generating Hamiltonian $H \circ \phi_t^* = H$.
(in the autonomous case)

Example:

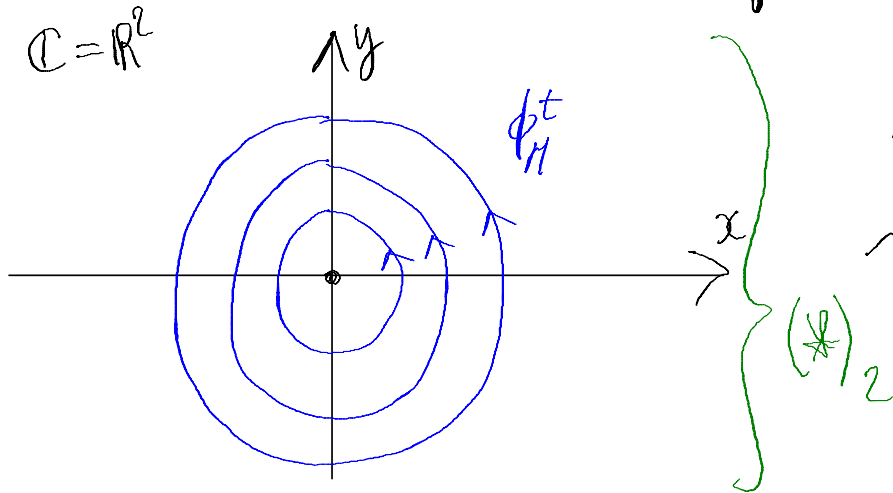
$$M = \mathbb{C} = \mathbb{R}^2, \quad \omega = dx \wedge dy,$$

$$H = |z|^2 = x^2 + y^2$$

Hamiltonian flow?

Hamiltonian flows 1) preserve the symplectic form,
 $(\phi_H^t)^* \omega = \omega$
 2) preserve their generating Hamil
 $H \circ \phi_H^t = H$.
 (in the *autonomous case*)

Example: $M = \mathbb{C} = \mathbb{R}^2$, $\omega = dx \wedge dy$,
 $H = |z|^2 = x^2 + y^2$



Note that $\phi_H^n = \text{id}$.
 \rightarrow Defines an S^1 -action.

More generally:

Def.: A smooth S^1 -action is called **Hamiltonian** iff it is induced by a Hamiltonian flow.

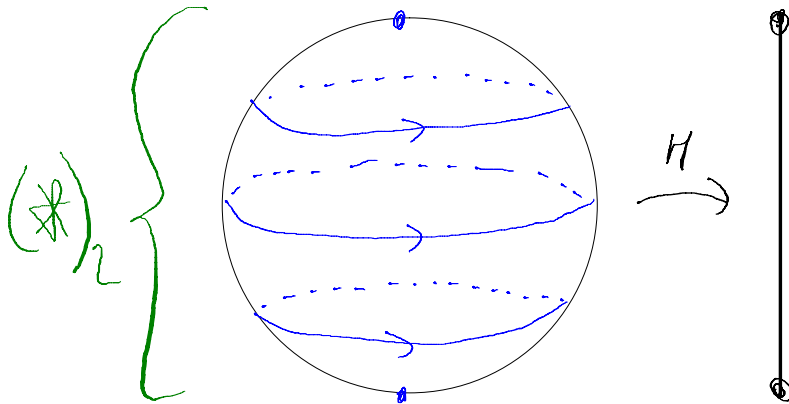
Example: $M = S^2$, $\omega =$ area form from $S^2 \subseteq \mathbb{R}^3$.
 $H(x, y, z) = z$

Hamiltonian flow?

More generally:

Def.: A smooth S^1 -action is called **Hamiltonian** iff it is induced by a Hamiltonian flow.

Example: $M = S^2$, $\omega =$ area form from $S^2 \subseteq \mathbb{R}^3$.
 $H(x, y, z) = z$



Hamiltonian flow
 $=$ rotation around
 z -axis.

Hamiltonian torus actions:

Def: Two Hamiltonian circle actions *commute* if their Hamiltonians H, F satisfy:

$$\{H, F\} = \omega(X_H, X_F) = 0$$

(Poisson bracket)

Fact: $\{H, F\} = 0 \Rightarrow \phi_H^t \circ \phi_F^s = \phi_F^s \circ \phi_H^t$.

$\Rightarrow (H, F)$ induce a $(T^2 = S^1 \times S^1)$ -action.

Def: A torus action $T^k \curvearrowright M$ is called *Hamiltonian* if it is of the above type.

Def: The map: $\mu = (H_1, \dots, H_k): M \rightarrow \mathbb{R}^k$ is called a *moment map*.

Such moment maps have remarkable properties!

Thm: (Atiyah / Guillemin — Sternberg)

The image of the moment map

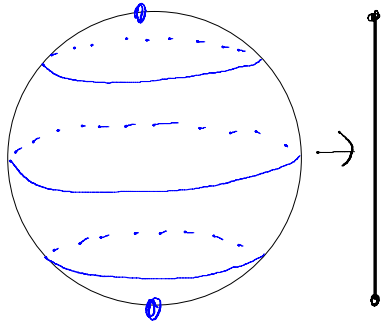
$$\Delta := \mu(U) \subseteq \mathbb{R}^k$$

is a convex rational polytope.

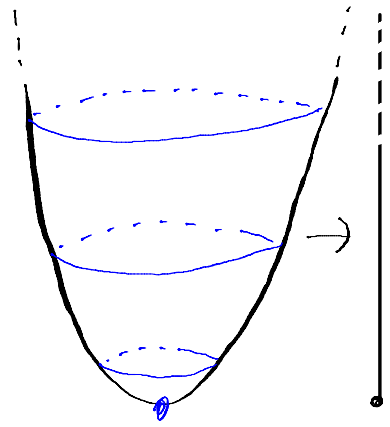
Def: The polytope Δ is called moment polytope.

§1. Toric manifolds

Recall:



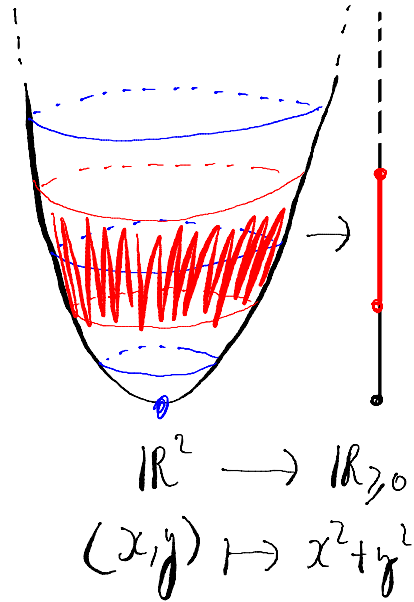
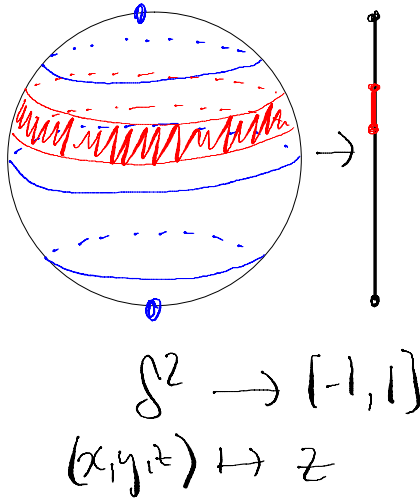
$$S^2 \rightarrow [-1, 1]$$
$$(x, y, z) \mapsto z$$



$$\mathbb{R}^2 \rightarrow \mathbb{R}_{\geq 0}$$
$$(x, y) \mapsto x^2 + y^2$$

§1. Toric manifolds

Recall:



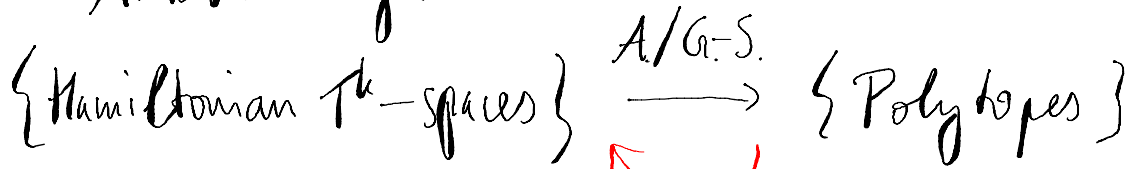
$(\mathbb{R})_4$

Remark:

The area of the **red slices** is proportional to the length of the **red segments**.

i.e. the moment map intertwines the geometry of Δ with the symplectic geometry of M .

Ambitious goal:



Reconstruct the manifold ??

Ambitious goal:

$\{\text{Hamiltonian } T^k\text{-spaces}\} \xrightarrow{A/G\text{-S.}} \{\text{Polytopes}\}$

true in a subset.

Delzant's theorem:

$\{\text{Toric symplectic mfd's}\} \xrightarrow{\cong} \{\text{Delzant polytopes}\} \cong$
Delzant construction.

Def.: (M^{2n}, ω) is called **toric** if there is an effective Hamiltonian T^n -action.

We get the "philosophy":

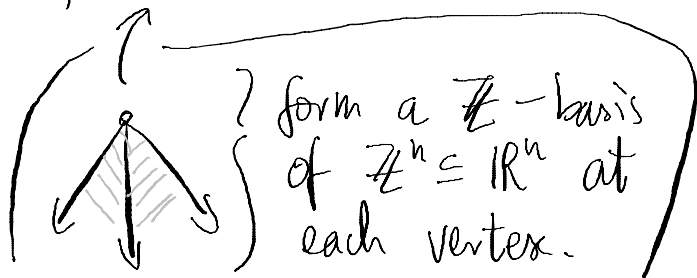
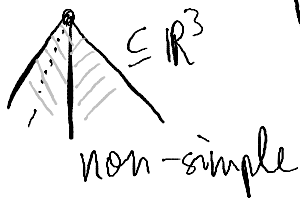
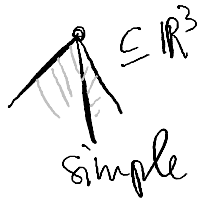
Symplectic geometry of toric manifolds \leftrightarrow Combinatorics of Delzant polytopes

For us: 1) Embedding problems (balls, ellipsoids...)

2) Lagrangian submanifolds, exotic tori:
Chekanov, Vianna et....

Def.: A rational polytope $\Delta \subseteq \mathbb{R}^n$ is **Delzant** if it is simple, smooth.

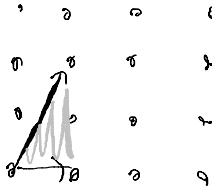
n facets at each vertex



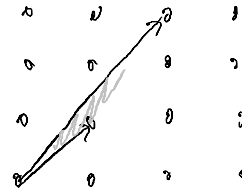
Smoothness of polytopes:



Smooth.

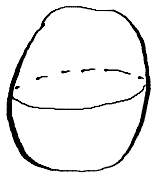


non-smooth.

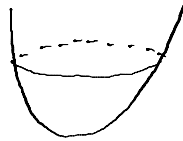


Smooth.

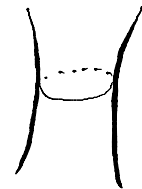
Examples: 2-dimensional:



$$S^2 \rightarrow [-1, 1]$$



$$\mathbb{C} \rightarrow \mathbb{R}_{\geq 0}$$



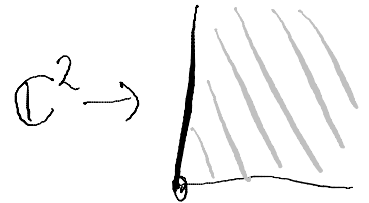
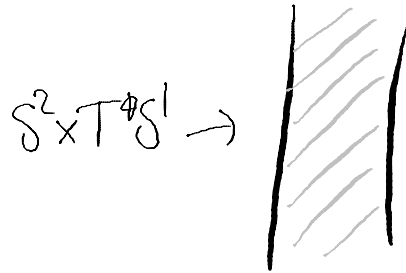
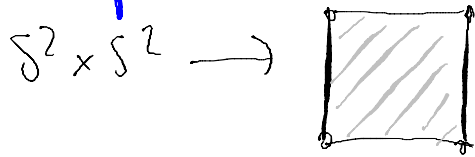
$$S^1 \times \mathbb{R} \rightarrow \mathbb{R}$$



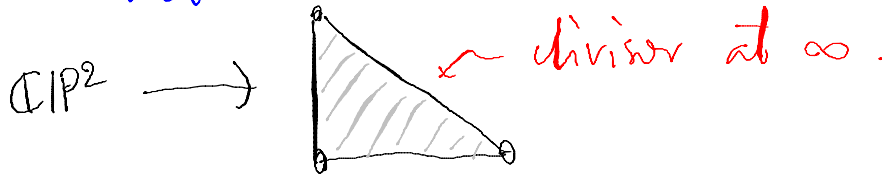
compact

non-compact

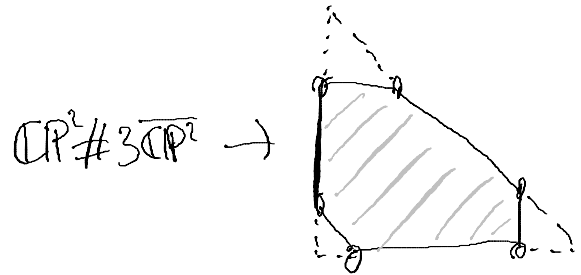
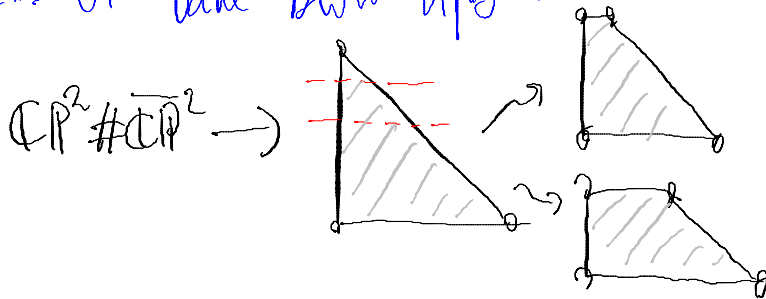
4-dimensional:
take products...



... or not ...

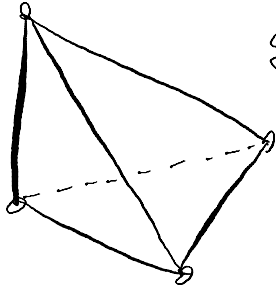


... or take blow-ups:

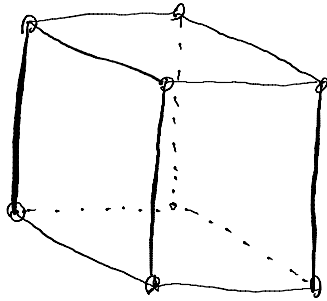


6-dimensional :

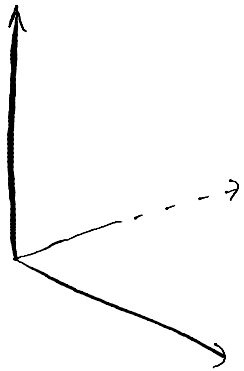
$\mathbb{C}P^3 \rightarrow$



$S^2 \times S^2 \times S^2$



\mathbb{C}^3

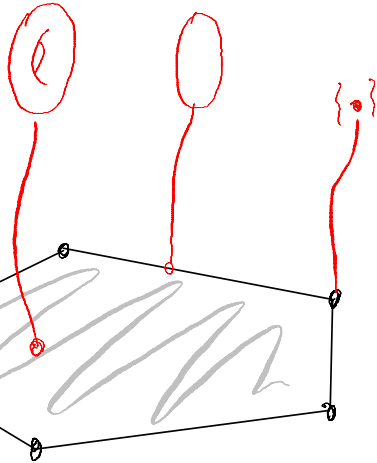


Fibration structure :

M



Δ



Recall : Hamiltonians are invariant under their flows,
 $\Rightarrow \mu(t.x) = \mu(x)$

In the toric case :

fibers = orbits of T^n -action.

$\mu : M \rightarrow \Delta$ is a quotient map.
 \uparrow
 T^n

Sh. Example: $\mathbb{C}P^2$

$$\mathbb{C}P^2 = \{[z_1:z_2:z_3]\},$$

Idea: Start with \mathbb{C}^3 and construct $\mathbb{C}P^2$

Symplectic: (\mathbb{C}^3, ω_0) $(\mathbb{C}P^2, \omega_{FS})$

Can be done by symplectic reduction.

Toric structure on \mathbb{C}^3 :

$$T^3 \curvearrowright \mathbb{C}^3 : (e^{i\theta_1}, e^{i\theta_2}, e^{i\theta_3}), (z_1, z_2, z_3) = (e^{i\theta_1} z_1, e^{i\theta_2} z_2, e^{i\theta_3} z_3)$$

generated by:

$$\mu: \mathbb{C}^3 \rightarrow \mathbb{R}_{\geq 0}^3 \\ (z_1, z_2, z_3) \mapsto (|z_1|^2, |z_2|^2, |z_3|^2)$$

Take $S^1 \subseteq T^3$, $e^{i\theta} H(e^{i\theta}, e^{i\theta}, e^{i\theta})$ subtorus

induced by $H(z_1, z_2, z_3) = |z_1|^2 + |z_2|^2 + |z_3|^2$
 $= \mu_1 + \mu_2 + \mu_3$
 $= \langle \mu, (1, 1, 1) \rangle$. induced Hamiltonian.

Consider $H^{-1}(1) = S^5 \subseteq \mathbb{C}^3$: Since ϕ_H^t preserves $H^{-1}(c)$

Hopf fibration. $\left\{ \begin{array}{l} H^{-1}(1) \stackrel{S^1}{\cong} S^5 \hookrightarrow \mathbb{C}^3 \\ \downarrow \\ \mathbb{C}P^2 \end{array} \right.$

Take $S^1 \subseteq T^3$, $e^{i\theta} H(e^{i\theta}, e^{i\theta}, e^{i\theta})$ subtorus

induced by $H(z_1, z_2, z_3) = |z_1|^2 + |z_2|^2 + |z_3|^2$
 $= \mu_1 + \mu_2 + \mu_3$
 $= \langle \mu, (1, 1, 1) \rangle$. induced Hamiltonian.

Consider $H^{-1}(1) = S^5 \subseteq \mathbb{C}^3$: Since ϕ_H^t preserves $H^{-1}(c)$

Symplectic reduction $\left\{ \begin{array}{l} H^{-1}(1) \stackrel{S^1}{\cong} S^5 \hookrightarrow (\mathbb{C}^3, \omega_0) \\ \downarrow \\ (\mathbb{C}P^2, \omega_{FS}) \end{array} \right.$

Q: Where is the toric structure?

We want $T^2 \circlearrowleft \mathbb{C}P^2$ Hamiltonian.

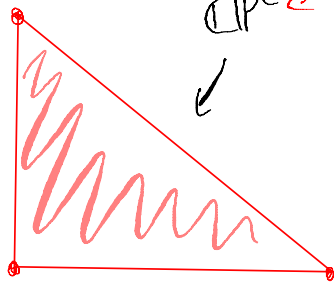
$$T^3 \circlearrowleft S^5 \hookrightarrow (\mathbb{C}^3, \omega_0) \circlearrowleft T^3$$



$$T^2 \cong T/S^1 \circlearrowleft (\mathbb{C}P^2, \omega_{FS})$$

↑ "residual" action.

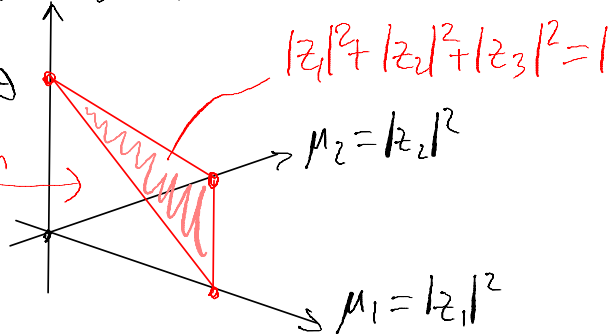
Moment maps:



$\mathbb{C}P^2$ ← reduction

$$S^5 \subseteq \mathbb{C}^3 \quad \mu_3 = |z_3|^2$$

(inclusion)



§3. Symplectic Reduction

Idea: $M \curvearrowright G$ smooth **free** group action $\Rightarrow M/G$ ^{quotient} manifold.

$(M, \omega) \curvearrowright G$ Hamiltonian group action $\Rightarrow (M, \tilde{\omega})$ ^{symplectic} quotient manifold.
& some conditions

Thm: (Marsden - Weinstein, ... for torus actions)

Let $M \curvearrowright T^k$ Hamiltonian torus action with moment map
 $\mu: M \rightarrow \mathbb{R}^k$.

Let $c \in \mathbb{R}^k$ s.t.h. $\mu^{-1}(c) \curvearrowright T^k$ freely.

$\Rightarrow \exists \tilde{\omega}$ symplectic form on $\mu^{-1}(c)/T^k =: \tilde{M}$ s.t.h.

$$\begin{array}{ccc} \mu^{-1}(c) & \xrightarrow{z} & (M, \omega) \\ \downarrow \pi & & \\ \tilde{M} & & (\tilde{M}, \tilde{\omega}) \end{array}$$

$$\pi^* \tilde{\omega} = z^* \omega$$

Exercises:

(See last pages for hints)

① Check that Hamiltonian flows preserve the symplectic form and the generating Hamiltonian

$$(\phi_H^t)^* \omega = \omega, \quad H \circ \phi_H^t = H$$

② Compute the Hamiltonian flows for:

i) $M = \mathbb{R}^2$, $\omega = dx \wedge dy$, $H(x, y) = x^2 + y^2$

ii) $M = S^2$, $\omega = \text{area form}$, $H(x, y, z) = z$
(from $S^2 \hookrightarrow \mathbb{R}^3$ as round sphere)

③ Check that they indeed induce circle actions!
(On the Poisson bracket)

i) Let $F, G \in C^\infty(M)$ s.t. $\{F, G\} = 0$. Check that F is constant along ϕ_G^t
(G $\xrightarrow{\quad}$ ϕ_G^t)

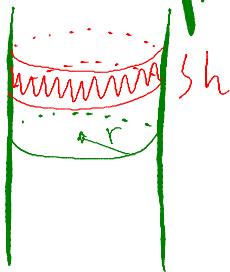
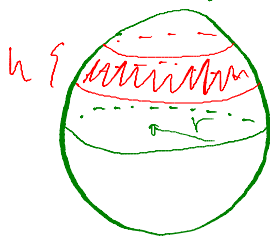
ii) Check that $X_{\{F,G\}} = [X_F, X_G]$
 (here $[\cdot, \cdot]$ is the Lie bracket of
 vector fields)

iii) Deduce the claim from the fact:

$$\{F, G\} = 0 \stackrel{(+)}{\Rightarrow} \phi_F^t \circ \phi_G^s = \phi_G^s \circ \phi_F^t$$

iv) Does the converse of (+) hold?
 Give a counterexample or a proof.

(4) Prove Archimedes' principle, i.e. the red slices
 have equal areas.



Can you move it without
 differential geometry (like Archimedes)?
 I can't....

⑤ (On the Delzant condition of polytopes)

i) Let $v \in \mathbb{Z}^2 \setminus \{0\}$. Is there always $w \in \mathbb{Z}^2 \setminus \{0\}$ s.t. the vertex formed by (v, w) is smooth?

If not: Counterexample. If yes, prove it and discuss uniqueness of w .

ii) Show that any two Delzant vertices are equivalent under $\text{GL}(n, \mathbb{Z})$.

iii) Let $B(r) := \{x \in \mathbb{R}^{2n} \mid \|x\| \leq r\}$ the Euclidean ball. Compute its image under the standard moment map of \mathbb{R}^{2n} .

Use ii) to deduce that every vertex of a Delzant moment polytopes gives a symplectic Ball embedding. (See also Felix's talk)

there are some computational rules that may come in handy for exercises ①-③:

L_X : Lie derivative, $i(X)$: contraction, d : exterior derivative.

on vector fields: $L_X(Y) = [X, Y]$ ("Cartan's magic formula")

on differential forms: $L_X \alpha = d i(X) \alpha + i(X) d \alpha$

$$L_X d \alpha = d L_X \alpha$$

- ① Differentiate and use $\frac{d}{dt}(\phi_H^t)^*(\circ) = L_{X_H}(\circ)$
- ② Choose smart coordinates (especially on S^2 ...)
- ③ i), ii): Differentiate
iv) Take the easiest (non-constant) functions on $\mathbb{R}^2 = \{(x, y)\}$
- ⑤ ii) Can be proved by a one-line sentence.